

# TAME TOPOLOGY AND O-MINIMAL STRUCTURES

## Outline of Lectures

- I. An Introduction to Definability and Quantifier Elimination
- II. The Semialgebraic case
- III. O-minimality and Some Basic Properties
- IV. Examples and Some Further Properties
- V. VC Dimension and Applications

# An Introduction to Definability

For which  $x$  do we have

$$\exists y \begin{bmatrix} ax + by > e_1 \\ cx + dy \leq e_2 \end{bmatrix} \quad (*)$$

where  $a, b, c, d, e_1, e_2 \in \mathbb{R}$ . Want

$$\{x \in \mathbb{R} \mid \text{statement } (*) \text{ holds for } x\}.$$

We also can replace the constants  $a, b, c, d, e_1, e_2$  by variables  $u, v, w, z, s_1, s_2$  and ask for which  $u, v, w, z, s_1, s_2 \in \mathbb{R}$  do we have

$$\exists x \exists y \begin{bmatrix} ux + vy > s_1 \\ wx + zy \leq s_2 \end{bmatrix}. \quad (**)$$

That is, we want to know

$$\{(u, v, w, z, s_1, s_2) \in \mathbb{R}^6 \mid \\ (u, v, w, z, s_1, s_2) \text{ satisfies } (**)\}$$

These are simple examples of *definable sets*.

Before getting more precise, some further

## Examples

1.  $S = \{x \in \mathbb{R} \mid \sin \pi x = 0\}$

Observe  $S = \mathbb{Z}$ .

2. Let  $L = \{(m, n) \in \mathbb{R}^2 \mid m, n \in \mathbb{Z}\}$  be the integer lattice in  $\mathbb{R}^2$ . View  $L$  as a two-place relation on pairs of real numbers:

$$L(m, n) \iff m, n \in \mathbb{Z}.$$

Define

$$C = \left\{ (x, y) \in \mathbb{R}^2 \mid \exists u \exists v [L(u, v) \wedge (x - u)^2 + (y - v)^2 \leq 1/16] \right\}.$$

The set  $C$  is the set of all closed discs of radius  $1/4$  whose centers are points in  $L$ .

## Structures on the real numbers $\mathbb{R}$

- Fix a stock
  - i.  $\mathcal{F}$  of *basic functions*  $f: \mathbb{R}^k \rightarrow \mathbb{R}$ ,  
for  $k = 1, 2, 3, \dots$
  - ii.  $\mathcal{R}$  of *basic relations (subsets)*  
 $R \subseteq \mathbb{R}^k$ , for  $k = 1, 2, 3, \dots$ , such  
that

the “less than” relation  $< \subset \mathbb{R}^2$

(and equality) always is included  
in  $\mathcal{R}$ .

Refer to  $\mathcal{F}$  and  $\mathcal{R}$  together as a  
*language*  $\mathcal{L}$ .

- The real numbers  $\mathbb{R}$  together with the  
functions and relations included in  $\mathcal{L}$   
is called an  *$\mathcal{L}$ -structure* that in general  
we denote by  $\mathfrak{R}_{\mathcal{L}}$ .

Special structures will have special  
names.

## Examples

1.  $\mathcal{F} = \{+, \cdot, -\}$  where  $-: \mathbb{R} \rightarrow \mathbb{R}$  is given by  $x \mapsto -x$ , and  $\mathcal{R} = \{<\}$ . This is the language  $\mathcal{L}_{\mathbf{alg}}$  of the ordered field of real numbers, the structure denoted by  $\mathbb{R}_{\mathbf{alg}}$ .
2.  $\mathcal{F}$  contains  $+$  and, for each  $r \in \mathbb{R}$ , the scalar multiplication function  $\mu_r: \mathbb{R} \rightarrow \mathbb{R}$  given by  $x \mapsto rx$ , and  $\mathcal{R} = \{<\}$ . This is the ordered real vector space language  $\mathcal{L}_{\mathbf{lin}}$  for the real numbers, whose corresponding structure is denoted by  $\mathbb{R}_{\mathbf{lin}}$ .
3.  $\mathcal{F} = \{+, \cdot, -, \exp\}$  where  $\exp: \mathbb{R} \rightarrow \mathbb{R}$  is the exponential function  $x \mapsto e^x$  and  $\mathcal{R} = \{<\}$ . This is the language  $\mathcal{L}_{\mathbf{exp}}$  of the ordered exponential field of real numbers; the structure is denoted by  $\mathbb{R}_{\mathbf{exp}}$ .

## Terms

- Construct an expanded class of functions by repeated composition starting from the functions in  $\mathcal{F}$ . These are called *terms*.

## Examples

1. The  $\mathcal{L}_{\text{alg}}$ -terms are all integer coefficient polynomial functions

$$p(x_1, \dots, x_k) \text{ for } k = 1, 2, 3, \dots$$

2. The  $\mathcal{L}_{\text{lin}}$ -terms are all  $\mathbb{R}$ -linear functions

$$L(x_1, \dots, x_k) = \mu_{r_1} x_1 + \dots + \mu_{r_k} x_k.$$

## Formulas

- First the *basic formulas*
  - i.  $t_1 = t_2$  for terms  $t_1, t_2$ .
  - ii.  $R(t_1, \dots, t_k)$  where  $R$  is a  $k$ -place relation and  $t_1, \dots, t_k$  are terms.  
 Note that  $t_1 < t_2$  is a special case.
- Recursively, from the basic formulas construct
  - i. by boolean operations from formulas  $\varphi$  and  $\psi$ :
    - $\varphi \wedge \psi$  read as “ $\varphi$  and  $\psi$ ”
    - $\varphi \vee \psi$  read as “ $\varphi$  or  $\psi$ ”
    - $\neg\varphi$  read as “not  $\varphi$ ”
  - ii. by existential quantification over  $\mathbb{R}$  from a formula  $\varphi$ :
    - $\exists v \varphi$  read as “there exists  $v$  such that  $\varphi$ ”

**Caution** To get to the point more quickly I have mixed syntax and semantics.

## $\mathcal{L}$ -definable sets

For our purposes these are subsets of  $\mathbb{R}^k$ , for  $k = 1, 2, 3, \dots$ , specified as follows.

For each  $\mathcal{L}$ -formula  $\varphi$ , certain variables are bound to quantifiers and others are not. Call the latter *free variables*, and it is for these that we can substitute real numbers.

For an  $\mathcal{L}$ -formula  $\varphi$  list its free variables as  $x_1, \dots, x_k, z_1, \dots, z_m$ . Choose  $c_1, \dots, c_m \in \mathbb{R}$  and substitute them for  $z_1, \dots, z_m$ , respectively. Write  $\bar{c}$  for  $(c_1, \dots, c_m)$ . The set

$$D_{\varphi, \bar{c}} = \{(x_1, \dots, x_k) \in \mathbb{R}^k \mid \varphi(x_1, \dots, x_k, \bar{c}) \text{ is true}\} \subseteq \mathbb{R}^k$$

is an  *$\mathcal{L}$ -definable* subset of  $\mathbb{R}^k$ .

If  $\mathcal{L}$  is clear from context, we usually shall drop the  $\mathcal{L}$ .



## Comments

- We call the  $\bar{c}$  *parameters*; the division of the free variables in a formula into those which are parameter variables and those that are not can be made in arbitrarily.
- A function  $F: A \subseteq \mathbb{R}^m \rightarrow \mathbb{R}^n$  is said to be  $\mathcal{L}$ -definable if its graph, as a subset of  $\mathbb{R}^m \times \mathbb{R}^n$ , is  $\mathcal{L}$ -definable.
- If a function  $F(x_1, \dots, x_m)$  is definable, we can treat it as if it is a term.
- Similarly, we can treat a definable subset of  $\mathbb{R}^k$  as a basic relation in the language.

## Some Further Examples

1. Let  $f: \mathbb{R} \rightarrow \mathbb{R}$  be  $\mathcal{L}$ -definable, where  $\mathcal{L}$  contains  $\mathcal{L}_{\text{alg}}$ . Then  $\{x \in \mathbb{R} \mid f \text{ is convex in an interval around } x\}$  is  $\mathcal{L}$ -definable.
2. Let  $f: A \subset \mathbb{R}^k \rightarrow \mathbb{R}$  be  $\mathcal{L}$ -definable, where  $\mathcal{L}$  contains  $\mathcal{L}_{\text{alg}}$ . Then  $\{\bar{x} \in A \mid f \text{ is continuous at } \bar{x}\}$  is  $\mathcal{L}$ -definable. Similarly for differentiability.
3. Let  $f: \mathbb{R} \rightarrow \mathbb{R}$  be  $\mathcal{L}$ -definable, where  $\mathcal{L}$  contains  $\mathcal{L}_{\text{alg}}$ . If  $f$  is differentiable, then  $f'$  is  $\mathcal{L}$ -definable. Same for functions of several variables.
4. Let  $f: \mathbb{R} \rightarrow \mathbb{R}$  be  $\mathcal{L}$ -definable, where  $\mathcal{L}$  contains  $\mathcal{L}_{\text{alg}}$ . Then  $\{x \in \mathbb{R} \mid f \text{ is Lipschitz in an interval around } x\}$  is  $\mathcal{L}$ -definable.

5. Let  $A \subset \mathbb{R}^k$  be  $\mathbb{R}_{\text{alg}}$ -definable. Then there is a formula that expresses that “ $A$  is convex.” Same for any  $\mathcal{L}$  containing  $\mathcal{L}_{\text{alg}}$ .
6. Let  $A \subset \mathbb{R}^k$  be  $\mathcal{L}$ -definable, where  $\mathcal{L}$  is arbitrary. Then the topological closure of  $A$  in  $\mathbb{R}^k$  is  $\mathcal{L}$ -definable. Many other basic notions from point-set topology also are definable.
6. Let  $A \subset \mathbb{R}^k$  be  $\mathcal{L}$ -definable. Then all level sets of  $A$  are  $\mathcal{L}$ -definable.
7. Closed polyhedra in  $\mathbb{R}^k$  are  $\mathcal{L}_{\text{lin}}$ -definable.

**Guidelines** for which sets are definable:

- Defining formulas cannot be infinitely long.
- Quantification over real numbers only is allowed.

## Definability **set-theoretically**

The  $\mathcal{L}$ -definable subsets of  $\mathbb{R}^n$  for  $n = 1, 2, 3, \dots$  is the smallest collection  $\mathfrak{D} = \{\mathcal{D}_n \mid n \geq 1\}$  such that

1. Each  $D \in \mathcal{D}_n$  is a subset of  $\mathbb{R}^n$ ;
2.  $\mathbb{R}^n \in \mathcal{D}_n$ ;
3. The graph of each  $f: \mathbb{R}^n \rightarrow \mathbb{R}$  in  $\mathcal{F}$  is in  $\mathcal{D}_{n+1}$
4. Each  $R \subseteq \mathbb{R}^n$  in  $\mathcal{R}$  is in  $\mathcal{D}_n$
5. For all  $1 \leq i, j \leq n$ ,  $\{(x_1, \dots, x_n) \in \mathbb{R}^n \mid x_i = x_j\} \in \mathcal{D}_n$ ;
6. Each  $\mathcal{D}_n$  is closed under intersection, union, and complement;
7. If  $\pi: \mathbb{R}^n \rightarrow \mathbb{R}^m$  is a projection map  $(x_1, \dots, x_n) \mapsto (x_{i_1}, \dots, x_{i_m})$  and  $X \in \mathcal{D}_n$  then  $\pi(X) \in \mathcal{D}_m$ ;
8. If  $\pi$  is as above and  $Y \in \mathcal{D}_m$ , then  $\pi^{-1}(Y) \in \mathcal{D}_n$ ;
9. If  $X \in \mathcal{D}_{n+m}$  and  $\bar{b} \in \mathbb{R}^m$ , then  $\{\bar{a} \in \mathbb{R}^n \mid (\bar{a}, \bar{b}) \in X\} \in \mathcal{D}_n$ .

## Finer structure of definable sets

A definable set typically has several different definitions. We have the  $\mathcal{L}_{\text{alg}}$ -definitions of the unit interval  $[0, 1]$ :

$$\{x \in \mathbb{R} \mid 0 < x \wedge x < 1\}$$

$$\{x \in \mathbb{R} \mid \exists y \exists z x^2 + y^2 + z^2 = 1\}$$

$$\{x \in \mathbb{R} \mid \forall y \exists z x^2 + (y - z)^2 = 1\}.$$

**Maxim** Quantification adds complexity.

One goal of model theory is to attempt to analyze definable sets in a specific context by showing that definable sets can be defined by simple formulas.

**Quantifier elimination** All  $\mathcal{L}$ -definable sets can be defined by quantifier-free  $\mathcal{L}$ -formulas.

## Quantifier elimination for $\mathcal{L}_{\text{lin}}$ -definable sets

**Theorem.** *For every  $n = 1, 2, 3, \dots$ , every  $\mathcal{L}_{\text{lin}}$ -definable subset of  $\mathbb{R}^n$  can be defined by a quantifier-free  $\mathcal{L}_{\text{lin}}$ -formula.*

For convenience, write  $rx$  instead of  $\mu_r(x)$ , where  $r \in \mathbb{R}$ .

The theorem tells us that every  $\mathcal{L}_{\text{lin}}$ -definable subset of  $\mathbb{R}^n$  is a finite boolean combination (i.e., finitely many intersections, unions, and complements) of sets of the form

$$\{(x_1, \dots, x_n) \in \mathbb{R}^n \mid a_1x_1 + \dots + a_nx_n > b\}$$

where  $a_1, \dots, a_n, b$  are fixed but arbitrary real numbers.

The  $\mathcal{L}_{\text{lin}}$ -definable sets are called the *semilinear* sets.

By routine set theoretic manipulation, semilinear sets can be written as a finite union of the intersection of finitely many sets defined by conditions of the form

$$\begin{aligned} a_1x_1 + \cdots + a_nx_n + b &= 0 \\ c_1x_1 + \cdots + c_nx_n + d &> 0. \end{aligned}$$

Thus  $\mathcal{L}_{\text{lin}}$ -definability reduces (basically) to linear algebra, which we understand well.

### $\mathcal{L}_{\text{lin}}$ -definable subsets of $\mathbb{R}$

All  $\mathcal{L}_{\text{lin}}$ -definable subsets of  $\mathbb{R}$  are finite boolean combinations of sets of the form

$$\{x \in \mathbb{R} \mid ax > b\}.$$

**Geometrically** these are the union of finitely many (possibly unbounded) open intervals and points.

**Consequence** Neither  $\mathbb{Z}$  nor  $\mathbb{Q}$  is  $\mathcal{L}_{\text{lin}}$ -definable.

## Idea of the proof

Eliminate quantifiers one at a time (proceed inductively).

## Example

Eliminate the quantifier for the  $\mathcal{L}_{\text{lin}}$ -definable set

$$\{x \in \mathbb{R} \mid \exists y [2x - 3y > 2 \wedge 4x - 2y \leq 0]\}$$

High school algebraic elimination.

**Question:** What about  $\mathcal{L}_{\text{alg}}$ -definability?

Next time



## Some General References

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